Magnetohydrodynamic and Ferrohydrodynamic Interactions on the Biomagnetic Flow and Heat Transfer Containing Magnetic Particles Along a Stretched Cylinder

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Abstract

In this paper, the laminar, incompressible and viscous flow of a biomagnetic fluid containing Fe_3O_4 magnetic particles, through a two dimensional stretched cylinder is numerically studied in the presence of a magnetic dipole. The extended formulation of Biomagnetic Fluid Dynamics (BFD) which involves the principles of MagnetoHydroDynamic (MHD) and FerroHydro-Dynamic (FHD) is adopted. The pressure terms are also taken consideration. The physical problem which is described by a coupled system of partial differential equations along with corresponding boundary conditions is converted to a coupled system of nonlinear ordinary differential equations subject

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to analogous boundary conditions utilizing similarity approach. The numerical solution is obtained by using an efficient technique which is based on a common finite difference method with central differencing, a tridigonal matrix manipulation and an iterative procedure. For verification proposes a comparison with previously published results is also made. The numerous results concerning the axial velocity, temperature, pressure, skin friction coefficient, rate of heat transfer and wall pressure parameter are presented for various values of the parameters. The axial velocity is decreased as the ferromagnetic number increases, temperature is enhanced with increasing values of the magnetic parameter.

Keywords: BFD, blood, magnetic particles, stretched cylinder, magnetic dipole, finite difference method.

List of Symbols

Velocity components [m/s]
Components of the cartesian system [m]
Radius of the cylinder [m]
Distance between the magnetic dipole to sheet [m]
Characteristic length of the cylinder [m]
Referred velocity [m/s]
Magnetic field of strength [A/m]
Fluid temperature [K]
Temperature of the sheet [K]
Curie temperature (Fluid temperature far away from the
sheet) [K]
Fluid magnetization [A/m]
Magnetic field parameter
Mean value of magnetic field strength
Stretched velocity [m/s]
Specific heat at constant pressure [J Kg ^{-1} K ^{-1}]
Dimensionless pressure
Velocity field
Dimensionless velocity component in x-direction
Strength of magnetic field at the source position.
Pyromagnetic coefficient [K ⁻¹]
Curvature parameter

Pr	Prandtl number			
Nu_x	Rate of heat transfer			
C_f	Skin friction coefficient			
Re	Local Reynolds number			
Greek sym	bols:			
η, ξ	Dimensionless coordinates			
$ heta_1, heta_2$	Dimensionless temperature			
$\theta'(0)$	Wall heat transfer gradient			
ψ	Stream function			
ρ	Fluid density [Kg/m ³]			
μ	Dynamic viscosity [Kg/ms]			
μ_0	Magnetic fluid permeability [NA ⁻²]			
v	Kinematical viscosity [m ² /s]			
σ	Electrical conductivity [S/m]			
ε_1	Convergence criteria			
ε	Dimensionless Curie temperature			
λ	Viscous dissipation parameter			
β	Ferromagnetic interaction parameter			
α	Dimensionless distance			
κ	Thermal conductivity [J/m s K]			
$ au_w$	Wall shear stress			
List of abb	reviations			
BFD	Biomagnetic fluid dynamic			
FHD	Ferrohydrodynamic			
MHD	Magnetohydrodynamic			
PDE	Partial differential equation			
ODE	Ordinary differential equation			
Subscripts	symbol			
$()_{mf}$	Indicates magnetic fluid			
$()_f$	Represent base fluid			
$\left(\right)_{a}$	Means magnetic particles (solid partic			

()_s Means magnetic particles (solid particles)

Introduction

The studies of biological fluid under the action of an applied magnetic field are known as biomagnetic fluid dynamics shortly BFD. One of the common examples of biomagnetic fluid is blood. Over the last few decades the application of nanoparticles especially magnetic nanoparticles adding with different type of biological fluid (blood) may open up a great interest of researchers due

to their wide range of applications such as in magnetic resonance imaging (MRI), in cancer therapy (hyperthermia), magnetic drug and gene delivery, magnetic separation [1–11] etc. Among all other nanoparticles, Iron oxide (magnetite) i.e. Fe_3O_4 has been plays a vital role in biomedical application because of their biocompatibility, biodegradability, facile synthesis, and ease that provides abundant functionalized for specific application.

Basically, BFD is related with principles of magnetohydrodynamic (MHD) and ferrohydrodynamic (FHD). Where, according to the model of FHD the fluids are assumed to be electrically non-conducting and the fluid flow is influenced under magnetization arising due to the presence of fluid magnetization. On the other hand, according to MHD the fluids are considered electrically conducting and the influence of magnetization or polarization is ignored. The first BFD model developed by Haik et al. [12] and it's based on the principle of FHD, where fluids are considered Newtonian and electrically non-conducting. In their study they found that the magnetization of the fluid has a significant impact on the flow under the influence of high gradient magnetic fields. Considering the concept of FHD and MHD, Tzirtzilakis [13] expanded BFD model in order to analyze the influence of magnetic field on blood flow where blood is assumed electrically conducting fluid. Recently, Murtaza et al. [14] studied extensively the BFD model which consist both principles of MHD and FHD under the influence of electrical conductivity and magnetization of blood and they found that the effect of FHD in the boundary layer stretching sheet flow is equally significant to that of MHD. Considering the viscoelastic property of the fluid, Misra et al. [15] examined the biomagnetic fluid also over a stretching sheet. The study of biomagnetic fluid under various conditions examined by various researchers like as Murtaza et al. [16, 17], Misra et al. [18], Tzirtzilakis et al. [19, 20] etc.

In 1995, Choi [21] was the first who deliver the idea of nanofluid where nanoparticles with higher thermal conductivity are used with base fluid like water, oil etc. to enhance their properties. The effect of magnetic field on nanofluid flow over a nonlinear stretching sheet studied by Misra et al. [22] and they found that velocity gradient of the fluid significantly influenced in presence of external magnetic field. Neuringer [23] studied the effects of magnetic fields and thermal gradient in a saturated ferro-fluid, where Thomson heat and Fourier heat conduction impact on magnetothermo-elastic porous medium explored by Elsayed et al. [24]. The impact of electrohydrodynamics nanoparticles Fe_3O_4 on ethylene glycol nanofluid in a sinusoidal enclosure examined by Sheikholeslami et al. [25]. Entropy generation in steady MHD flow due to a rotating porous disk in water based nanofluid considering the Cu, CuO, Al₂O₃ nanoparticles studied by Rashidi et al. [26]. The wide range application of BFD boundary layer flow and heat transfer through a stretched cylinder in presence of applied magnetic field has gained serious attention from the researchers. Ishak et al. [27] studied the laminar boundary layer flow along a stretching cylinder where Bachok et al. [28] conducted the study of heat transfer with prescribed heat flux through stretching cylinder. MHD boundary layer slip flow through stretched cylinder examined by Mukhopadhyay [29]. Qasim et al. [30] investigated the MHD Fe₃O₄-H₂O and Al₂O₃-H₂O nanofluid over a stretching cylinder with prescribed heat flux and numerical calculations carried out by using a shooting method. They found that heat transfer rate is increased with the increment of the values of the magnetic nanoparticles volume fraction. Nadeem et al. [31] prescribed the characteristics of non-Newtonian fluid along a stretching cylinder in the presence of magnetic dipole. The effect of magnetic dipole on Newtonian ferrofluid through a stretchable cylinder studied by Tahir et al. [32] and they concluded that rate of heat transfer increased with augment of curvature parameter. Most of the above studies are studied on stretched cylinder either considering principles of MHD or FHD or both, where fluid is assumed as electrically conducting or non-conducting and water is considered as a based fluid. To our knowledge, the blood flow containing magnetic nanoparticles and considering the electrical conductivity along with the effect of polarization/magnetization has not studied widely yet.

The ultimate purpose of the study is to seek the influence of blood flow and heat transfer with magnetic particles (Fe_3O_4) through stretched cylinder in the presence of a magnetic dipole, where blood is considered as a Newtonian and electrical conducting fluid. Our base studies are [30–32, 41] and we apply the considerations and the extension on the mathematical model in an analogous manner as the study [14]. Thus, both principles of FHD and MHD are adopted in this model and consequently pressure term is also taken into consideration. The momentum equations and the energy equation are made dimensionless by utilizing similarity transformations. The numerical solution is carried out by applying an efficient numerical technique which is based on the common finite difference method with central differencing, a tridiagonal matrix manipulation and an iterative procedure. The effect of pertinent parameters on velocity, temperature and pressure profile as well as wall heat transfer, skin friction coefficient and pressure gradient are examined and discussed in detail. It is hoped that this study will contribute to the understanding of basic mechanisms utilized for applications in biomedicine, MRI and cancer treatment.

Mathematical Flow Model

We consider an electrically conducting biomagnetic fluid (blood) containing magnetic particles like Fe₃O₄ the flow of which is considered to be steady, viscous, axis symmetric and incompressible passing through a stretchable cylinder of radius a. The schematic system of flow is demonstrated at Figure 1 where x axis is along and r axis is normal to the cylinder and assumed that cylinder is stretched along x direction with velocity $U_w = \frac{u_0 x}{l}$, where l is the characteristics length and u_0 referred to velocity. The temperature at the surface and ambient fluid temperature is T_w and T_c , respectively where $T_w < T_c$. Also assume that blood flow is subjected to a magnetic field of strength H that produced a magnetic dipole, which lies on the center on r axis and placed at below the surface at distance c. However, the Lorentz force which is due to the electrical conductivity of blood, is not negligible in the flow region where the magnetic field is applied and should be taken under consideration.

Under the above considerations we extend the idea of [30–32, 41] and here the continuity, momentum and energy equations are in following form:

Continuity equation

$$\frac{\partial}{\partial x}(ru) + \frac{\partial}{\partial r}(rv) = 0 \tag{1}$$



Figure 1 Schematic diagram of flow problem.

Momentum equations

$$u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial r} = -\frac{1}{\rho_{mf}}\frac{\partial p}{\partial x} + \frac{\mu_{mf}}{\rho_{mf}}\left(\frac{1}{r}\frac{\partial u}{\partial r} + \frac{\partial^2 u}{\partial r^2} + \frac{\partial^2 u}{\partial x^2}\right) - \frac{\sigma_{mf}}{\rho_{mf}}B_0^2 u + \frac{1}{\rho_{mf}}\mu_0 M_1\frac{\partial H}{\partial x}$$
(2)

$$u\frac{\partial v}{\partial x} + v\frac{\partial v}{\partial r} = -\frac{1}{\rho_{mf}}\frac{\partial p}{\partial r} + \frac{\mu_{mf}}{\rho_{mf}}\left(\frac{1}{r}\frac{\partial v}{\partial r} + \frac{\partial^2 v}{\partial r^2} + \frac{\partial^2 v}{\partial x^2} - \frac{v}{r^2}\right)$$
(3)

Energy equation

$$(\rho C_p)_{mf} \left(u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial r} \right) + \mu_0 T \frac{\partial M_1}{\partial T} \left(u \frac{\partial H}{\partial x} + v \frac{\partial H}{\partial r} \right)$$
$$= \kappa_{mf} \left(\frac{1}{r} \frac{\partial T}{\partial r} + \frac{\partial^2 T}{\partial r^2} + \frac{\partial^2 T}{\partial x^2} \right)$$
(4)

With associated boundary conditions

$$u = U_w = \frac{u_0 x}{l}, \ v = 0, \ T = T_w$$
 at $r = a$ (5)

$$u \to 0, \ T \to T_c, \ P + \frac{1}{2}\rho q^2 = \text{constant} \qquad \text{at } r \to \infty$$
 (6)

Where, u and v are the velocity component along x and r axis, respectively ($\vec{q} = (u, v)$). Also $P, \rho, \mu, \sigma, \mu_0, M_1, H, C_p, \kappa$ denotes the biomagnetic fluid pressure, density, dynamic viscosity, electrical conductivity, magnetic permeability, magnetization, magnetic field of strength, specific heat at constant pressure and thermal conductivity respectively. B_0 is the mean value of steady magnetic field of strength inside the flow field. The symbol ($)_{mf}$, represents the magnetic fluid. In Equation (2), the term $\mu_0 M_1 \frac{\partial H_1}{\partial x}$ indicates the components of ferromagnetic body force per unit; while the term $\mu_0 T \frac{\partial M_1}{\partial T} (u \frac{\partial H}{\partial x} + v \frac{\partial H}{\partial r})$ in Equation (4) accounts for heating due to adiabatic magnetization. These terms are well known as FHD. In Equation (2) the term $\frac{\sigma_{mf}}{\rho_{mf}} B_0^2 u$ represents force per unit volume towards x-direction and arises due to the electrical conductivity of the fluid (blood). These term arise because of MHD.

Considering the studies of [23] and [32], the magnetic dipole gives rise to a magnetic field sufficiently strong to saturate the biofluid and its scalar potential is given by

$$V = \frac{\alpha}{2\pi} \frac{x}{x^2 + (r+c)^2}$$
(7)

Here, $\alpha = \sqrt{\frac{u_0}{v_f}c^2}$ is a dimensionless distance and $\alpha = \gamma$ where γ indicates the strength of magnetic field at the source position.

Therefore, the magnitude of the magnetic field of intensity i.e. $\|\vec{H}\| = H$ is given by

$$\|\vec{H}\| = H(x,r) = \sqrt{H_x^2 + H_r^2} = \frac{\gamma}{2\pi} \frac{x^2}{x^2 + (r+c)^2}$$
(8)

And H_x, H_r are the components of the magnetic field $\vec{H} = (H_x, H_r)$ given by

$$H_x(x,r) = -\frac{\partial V}{\partial x} = \frac{\gamma}{2\pi} \frac{x^2 - (r+c)^2}{(x^2 + (r+c)^2)^2}$$
(9)

$$H_r(x,r) = -\frac{\partial V}{\partial r} = \frac{\gamma}{2\pi} \frac{2x(r+c)}{(x^2 + (r+c)^2)^2}$$
(10)

After calculations of (9) and (10), the component takes the form

$$\frac{\partial H}{\partial x} = -\frac{\gamma}{2\pi} \frac{2x}{(r+c)^4} \tag{11}$$

$$\frac{\partial H}{\partial r} = -\frac{\gamma}{2\pi} \left(\frac{-2}{(r+c)^3} + \frac{4x^2}{(r+c)^5} \right) \tag{12}$$

Thus, the magnetic field intensity H can be expressed as

$$H(x,r) = \frac{\gamma}{2\pi} \left(\frac{1}{(r+c)^2} - \frac{x^2}{(r+c)^4} \right)$$
(13)

The variation of magnetization M_1 with temperature T is defined by a linear relation [32]

$$M_1 = K(T_c - T) \tag{14}$$

Where, K represents the pyromagnetic coefficient and T_c is the Curie temperature.

The thermo-physical factors of magnetic particles are defined as [30]

$$\mu_{mf} = \mu_f (1-\phi)^{-2.5}, (\rho C_p)_{mf} = (1-\phi)(\rho C_p)_f + \phi(\rho C_p)_s,$$

$$\rho_{mf} = (1-\phi)\rho_f + \phi\rho_s,$$

$$\sigma_{mf} = (1-\phi)\sigma_f + \phi\sigma_s, \frac{\kappa_{mf}}{\kappa_f} = \frac{(\kappa_s + 2\kappa_f) - 2\phi(\kappa_f - \kappa_s)}{(\kappa_s + 2\kappa_f) + \phi(\kappa_f - \kappa_s)}$$
(15)

Here, ϕ indicates the volume fraction where, $\phi = 0$ corresponds to regular fluid. Note that ()_f and ()_s signifies the base fluid (blood) and magnetic particles (Fe₃O₄).

Solution Procedure

For the implementation of the numerical solution we introduce the similarity transformation in order to make the momentum and energy equations dimensionless [32]

$$\eta(r) = \frac{r^2 - a^2}{2a} \left(\frac{U_w}{v_f x}\right)^{\frac{1}{2}} = \frac{r^2 - a^2}{2a} \left(\frac{u_0}{v_f l}\right)^{\frac{1}{2}}$$

$$\xi(x) = \left(\frac{u_0}{v_f l}\right)^{\frac{1}{2}} x, \psi(\xi, \eta) = \left(\frac{u_0 v_f}{l}\right)^{\frac{1}{2}} a x f(\eta)$$

$$\theta(\xi, \eta) = \frac{T_c - T}{T_c - T_w} = \theta_1(\eta) + \xi^2 \theta_2(\eta)$$

$$P(\xi, \eta) = \frac{P}{\frac{u_0 \mu_f}{l}} = -[P_1(\eta) + \xi^2 P_2(\eta)]$$
(16)

Where, $\psi(\xi, \eta), \theta(\xi, \eta)$ and $P(\xi, \eta)$ are the stream function, the dimensionless temperature and pressure respectively. The continuity equation is satisfied considering the velocity components as follows

$$\begin{cases} u = \frac{1}{r} \frac{\partial \psi}{\partial r} \\ v = -\frac{1}{r} \frac{\partial \psi}{\partial x} \end{cases}$$
(17)

We substitute Equations (11) to (17) into Equations (2) to (4) and then equating the coefficients of equal power of ξ up to ξ^2 , we get

$$(1+2\eta D)f'''+2Df''-(1-\phi)^{2.5}\left(1-\phi+\phi\frac{\sigma_s}{\sigma_f}\right)Mf'$$
$$-(1-\phi)^{2.5}\left(1-\phi+\phi\frac{\rho_s}{\rho_f}\right)(f'^2-ff'')$$
$$+2(1-\phi)^{2.5}P_2-(1-\phi)^{2.5}\frac{2\beta\theta_1}{(\eta+\alpha)^4}=0$$
(18)

$$(1+2\eta D)^{2}(1-\phi)^{2.5}P_{1}' - (1+2\eta D)^{2}f'' + (1-\phi)^{2.5}\left(1-\phi+\phi\frac{\rho_{s}}{\rho_{f}}\right)(Df^{2} - (1+2\eta D)ff') = 0$$
(19)

$$(1+2\eta D)^2 (1-\phi)^{2.5} P_2' = 0$$
⁽²⁰⁾

$$(1+2\eta D)\theta_1''+2\theta_2+2D\theta_1' + \frac{\kappa_f}{\kappa_{mf}}\left(\left(1-\phi+\phi\frac{(\rho C_p)_s}{(\rho C_p)_f}\right)\operatorname{Pr} f\theta_1'+\frac{2\beta\lambda f(\theta_1-\varepsilon)}{(\eta+\alpha)^3}\right) = 0$$
(21)

$$(1+2\eta D)\theta_2''+2D\theta_2'$$

$$+\frac{\kappa_f}{\kappa_{mf}} \left(\left(1 - \phi + \phi \frac{(\rho C_p)_s}{(\rho C_p)_f} \right) \Pr\left(f \theta'_2 - 2f' \theta_2 \right) \\ -2\beta\lambda(\theta_1 - \varepsilon) \left[\frac{f'}{(\eta + \alpha)^4} + \frac{2f}{(\eta + \alpha)^5} \right] + \frac{2\beta\lambda f \theta_2}{(\eta + \alpha)^3} \right) = 0$$
(22)

And the boundary conditions (5) and (6) take the following form

$$f = 0, f' = 1, \theta_1 = 1, \theta_2 = 0$$
 at $\eta = 0$ (23)

$$f' \to 0, \ \theta_1 \to 0, \ \theta_2 \to 0, \ P_1 \to -P_{\infty}, \ P_2 \to 0 \qquad \text{at } \eta \to \infty$$
 (24)

Here the dimensionless parameters that appear in the above equations are defined as

Ferromagnetic interaction parameter $\beta = \frac{\gamma}{2\pi} \frac{\mu_0 K (T_c - T_w) \rho_f}{\mu_f^2}$; Magnetic field parameter $M = \frac{\sigma_f B_0^2 l}{u_0 \rho_f}$; viscous dissipation parameter $\lambda = \frac{u_0 \mu_f^2}{lk_f (T_c - T_w) \rho_f}$; Curie temperature $\varepsilon = \frac{T_c}{T_c - T_w}$; Curvature parameter $D = (\frac{lv_f}{u_0 a^2})^{\frac{1}{2}}$; Dimensionless distance $\alpha = (\frac{u_0}{v_f})^{\frac{1}{2}}c$; Prandtl number $\Pr = \frac{(\mu C_p)_f}{\kappa_f}$.

Numerical Technique

In this section we describe the numerical solution of the problem where we apply an approximate technique that has better stability characteristics than a classical Runge-Kutta combined with a shooting method, is simple, accurate and efficient. The detail study of this technique can be found in [14, 40]. The most important features of this technique are:

- (1) It is based on the common finite difference method with central differencing.
- (2) On a tridiagonal matrix manipulation, and
- (3) On an iterative procedure

According [14, 40], we can write the momentum Equation (19) is following way:

$$(1+2\eta D)f'''+2D f''-(1-\phi)^{2.5}$$

$$\left((1-\phi+\phi\frac{\sigma_s}{\sigma_f})Mf'+\left(1-\phi+\phi\frac{\rho_s}{\rho_f}\right)f'^2\right)+(1-\phi)^{2.5}$$

$$\left(1-\phi+\phi\frac{\rho_s}{\rho_f}\right)ff''=(1-\phi)^{2.5}\frac{2\beta\theta_1}{(\eta+\alpha)^4}-2(1-\phi)^{2.5}P_2$$
(25)

By putting $y(x) = f'(\eta)$, the Equation (25) can be considered as a second order linear differential equation and provided that P_2 and $f(\eta)$ are assumed to be known functions.

In this case Equation (25) can be written as

$$(1+2\eta D)(f')'' + \left(2 D + (1-\phi)^{2.5} \left(1-\phi+\phi\frac{\rho_s}{\rho_f}\right) f\right)(f')' \\ - \left((1-\phi)^{2.5} \left(1-\phi+\phi\frac{\sigma_s}{\sigma_f}\right) M + (1-\phi)^{2.5} \left(1-\phi+\phi\frac{\rho_s}{\rho_f}\right) f'\right) \\ f' = (1-\phi)^{2.5} \frac{2\beta\theta_1}{(\eta+\alpha)^4} - 2(1-\phi)^{2.5} P_2$$

Which takes the form

$$P(x)y''(x) + Q(x)y'(x) + R(x)y(x) = S(x)$$
(26)

Where,

$$P(x) = 1 + 2\eta \,\mathcal{D}, \ Q(x) = 2 \,D - (1 - \phi)^{2.5} \left(1 - \phi + \phi \frac{\rho_s}{\rho_f}\right) f,$$
$$R(x) = -(1 - \phi)^{2.5} \left(1 - \phi + \phi \frac{\sigma_s}{\sigma_f}\right) M$$

$$-(1-\phi)^{2.5} \left(1-\phi+\phi\frac{\rho_s}{\rho_f}\right) f',$$
$$S(x) = (1-\phi)^{2.5} \frac{2\beta\theta_1}{(\eta+\alpha)^4} - 2(1-\phi)^{2.5} P_2$$

Now Equation (26) can be solved by a common finite difference method, based on central differencing and tridiagonal matrix manipulation, before starting solution procedure, it's essential to give an initial guess for $f'(\eta)$ and $P_2(\eta)$ between $\eta = 0$ and $\eta = \eta_{\infty}(\eta \to \infty)$ which satisfy the boundary conditions of (23) and (24). For this we assume as initial distributions that,

$$f'(\eta) = 1 - \frac{\eta}{\eta_{\infty}}, \ \theta_1 = 1 - \frac{\eta}{\eta_{\infty}}, \ \theta_2 = \frac{1}{2} \left(\frac{\eta}{\eta_{\infty}}\right) \left(1 - \frac{\eta}{\eta_{\infty}}\right)$$

The $f(\eta)$ distribution is obtained by the integration from $f'(\eta)$ curve. The next step is to consider f, P_2 and θ_1 known and to determine a new estimation for $f'(\eta), (f'_{new})$ by solving the nonlinear Equation (26) using the above method. The $f(\eta)$ distribution is updated by integrating the new $f'(\eta)$ curves. These new profiles f and f' are then used to new inputs and so on. In this way the momentum Equation (25) and consequently (18) are solved iteratively until convergence up to a small quantity ε_1 is attained.

Following the same algorithm, Equations (21) and (22) with boundary conditions (23) and (24) are solved after $f(\eta)$ is obtained.

Now energy Equations (21) and (22) can be written in the form of Equation (26) that is

$$(1+2\eta D)\theta_1'' + \left(2 D + \frac{\kappa_f}{\kappa_{mf}} \left(1 - \phi + \phi \frac{(\rho C_p)_s}{(\rho C_p)_f}\right) \Pr f\right) \theta_1' - \frac{\kappa_f}{\kappa_{mf}} \frac{2\beta\lambda f}{(\eta+\alpha)^3} \theta_1 = \frac{\kappa_f}{\kappa_{mf}} \frac{2\beta\lambda f \varepsilon}{(\eta+\alpha)^3} - 2\theta_2$$
(27)

By setting $y(x) = \theta_1(\eta)$ in Equation (28), we get

$$P(x)y''(x) + Q(x)y'(x) + R(x)y(x) = S(x)$$
(28)

Where,

$$P(x) = 1 + 2\eta \mathbf{D}, \ Q(x)$$

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$$= 2D + \frac{\kappa_f}{\kappa_{mf}} \left(1 - \phi + \phi \frac{(\rho C_p)_s}{(\rho C_p)_f} \right) \Pr f,$$
$$R(x) = -\frac{\kappa_f}{\kappa_{mf}} \frac{2\beta\lambda f}{(\eta + \alpha)^3},$$
$$S(x) = \frac{\kappa_f}{\kappa_{mf}} \frac{2\beta\lambda f\varepsilon}{(\eta + \alpha)^3} - 2\theta_2$$

Similarly Equation (23) can be written as

$$(1+2\eta D)\theta_{2}'' + \left(2D + \frac{\kappa_{f}}{\kappa_{mf}} \left(1-\phi + \phi \frac{(\rho C_{p})_{s}}{(\rho C_{p})_{f}}\right) \Pr f\right) \theta_{2}' + \frac{\kappa_{f}}{\kappa_{mf}} \left(\frac{2\beta\lambda f \theta_{2}}{(\eta+\alpha)^{3}} - \left(1-\phi + \phi \frac{(\rho C_{p})_{s}}{(\rho C_{p})_{f}}\right) 2\Pr f'\right) \theta_{2}' = \frac{\kappa_{f}}{\kappa_{mf}} 2\beta\lambda(\theta_{1}-\varepsilon) \left[\frac{f'}{(\eta+\alpha)^{4}} + \frac{2f}{(\eta+\alpha)^{5}}\right]$$
(29)

Again setting $y(x) = \theta_2(\eta)$, Equation (30) are reduced in a second order differential equation and of the following form

$$P(x)y''(x) + Q(x)y'(x) + R(x)y(x) = S(x)$$
(30)

Where,

$$P(x) = 1 + 2\eta D, \ Q(x) = 2D + \frac{\kappa_f}{\kappa_{mf}} \left(1 - \phi + \phi \frac{(\rho C_p)_s}{(\rho C_p)_f} \right) \Pr f,$$
$$R(x) = \frac{\kappa_f}{\kappa_{mf}} \left(\frac{2\beta\lambda f \theta_2}{(\eta + \alpha)^3} - \left(1 - \phi + \phi \frac{(\rho C_p)_s}{(\rho C_p)_f} \right) 2\Pr f' \right),$$
$$S(x) = \frac{\kappa_f}{\kappa_{mf}} 2\beta\lambda(\theta_1 - \varepsilon) \left[\frac{f'}{(\eta + \alpha)^4} + \frac{2f}{(\eta + \alpha)^5} \right]$$

In this way we obtain θ_1 and θ_2 until the convergence up to a small quantity ε_1 is attained. Then now we obtain new estimates of P_1 and P_2 from Equations (19) and (20), respectively, which are already first order linear differential equation. This process is continuing until the trial convergence of the solution is attained. For the numerical solution we apply a step size $h = \Delta \eta = 0.01$, $\eta_{\min} = 0$ and $\eta_{\max} = 1$; and the solution is convergent with an approximation of 10^{-3} .

Validation

Before proceeding to the numerical calculation, it's necessary to check the accuracy of the numerical technique and for that we compared our present numerical results with those published in the study [32]. An indicative graphical representation of the comparison is given at Figures 2 and 3 where our results has been found in good agreement with those obtained in [32]. Furthermore, we also compared the rate of heat transfer for different values of Prandtl number Pr. These results are presented at Table 1 and also verify the good agreement with the results obtained in [32].

Results and Discussion

In this section we discuss the results presented graphically with respect of the effect of the dimensionless parameters for velocity, temperature, pressure, skin friction coefficient, rate of heat transfer and pressure gradient. In order to attain this, we need to put some realistic values which published previously and relative to this paper. So, we assume the fluid is blood and the magnetic



Figure 2 Comparison of velocity profile for $M = P = \phi = 0$, $\kappa_f = \kappa_{mf} = 1$.



Figure 3 Comparison of Temperature profile for $M = P = \phi = 0, \kappa_f = \kappa_{mf} = 1$.

Table 1 Comparison of the rate of heat transfer with [32] for various values of Pr when $M = P = \phi = 0, \kappa_f = \kappa_{mf} = 1$

Pr	Present Result	Tahir et al. [32]	Error
1	0.5131	0.5132769	0.0001769
1.3	0.5858	0.5982321	0.0182321
1.9	0.6324	0.6312902	0.0011098
4	0.8807	0.8892303	0.0085303
10	1.801	1.8002134	0.0007866

Table 2 Thermo-physical values of blood and Fe_3O_4							
Physical Properties	$C_p(jkg^{-1}K^{-1})$	$ ho(kgm^{-3})$	$\sigma(sm^{-1})$	$\kappa(Wm^{-1}K^{-1})$			
Blood	$3.9 imes 10^3$	1050	0.8	0.5			
Fe ₃ O ₄	670	5180	0.74×10^6	9.7			

particles are Fe_3O_4 , and following the literature [19, 20, 33–36] we adopt the values of properties of blood and Fe_3O_4 given in Table 2.

Whereas human body temperature $T_w = 37^{\circ}$ C [20], body Curie temperature is $T_c = 41^{\circ}$ C. For above values dimensionless temperature $\varepsilon = 78.5$ [14], viscous dissipation number $\lambda = 6.4 \times 10^{-14}$ [14] and

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Figure 4 Axial velocity profile $f'(\eta)$ for FHD, MHD and BFD.

dimensionless distance $\alpha = 1$ [19]. For numerical calculation the values of leading parameters Prandtl number Pr = 17, 21, 23, 25 [19], magnetic parameter M = 0.1, 0.5, 0.5, 0.7, 1, 5, 10 [37, 38], volume fraction $\phi = 0.0, 0.0001, 0.001, 0.005, 0.1, 0.15, 0.2$ [39], curvature parameter D =0.1, 0.2, 0.5, 1, 1.5, 2 [31, 32] and ferromagnetic interaction parameter $\beta =$ 0, 5, 10 [14]. Note down when $M = 0, \beta \neq 0$ indicates to pure ferrohydrodynamic flow (FHD), $M \neq 0, \beta = 0$ indicates to pure magnetohydrodynamic flow (MHD) and $M \neq 0, \beta \neq 0$ indicates to mixed FHD and MHD flow which appears in the biomagnetic fluid flow (BFD) [13].

The influence of magnetic particles volume fraction on FHD, MHD and BFD in axial velocity, pressure and temperature profile can be observed from Figures 4 to 7. Where Figure 4 indicate that the decrement of the axial velocity for BFD is greater than FHD and MHD. It also clears that when we added magnetic particles with base fluid like blood, the decrement of BFD is more pronounced than pure BFD fluid. From the pressure profile (see Figure 5) we see that in case of BFD pressure is more comfortable to control rather than FHD and MHD. On the other hand, from the temperature profiles (see Figures 6 and 7) we observed that in case of BFD, temperature



Figure 5 Pressure profile $P_1(\eta)$ for FHD, MHD and BFD.



Figure 6 Temperature profile $\theta_1(\eta)$ for FHD, MHD and BFD.



Figure 7 Temperature profile $\theta_2(\eta)$ for FHD, MHD and BFD.

is increased much better than FHD and MHD cases under the influence of magnetic particles. Moreover, in the absence of magnetic particles, MHD is increased much effectively than BFD and FHD cases.

Figures 8 to 11 demonstrate the effect of ferromagnetic number on the axial velocity, pressure and temperature profile. From the pressure profile it is evident that as β increases $P_1(\eta)$ is effectively reduced in the ferrohydrodynamic case especially for small values of η . Figures 10 to 11 show that the temperature profiles (see Figures 10 and 11) increase with raising values of β and its augment noticed when $\beta > 0$. The axial velocity $f'(\eta)$ is reduced with increment of the values of ferromagnetic number (see Figure 8). This is happening due to the fact that β is directly related to the Kelvin force.

Figures 12 to 15 present the variations of magnetic parameter on velocity, pressure and temperature distributions, respectively. It is apparent from Figure 12 that as magnetic parameter is increased, the axial velocity is reduced due to the fact that the presence of magnetic field produce Lorentz forces that act oppose to the flow. As the velocity is suppressed it is normal to see increment of the pressure profile as the values of M are enhanced. The reverse behavior can be seen for the temperature profiles (see Figures 14 and 15).



Figure 8 Influence of β on axial velocity profile $f'(\eta)$.



Figure 9 Influence of β on pressure profile $P_1(\eta)$.







Figure 11 Influence of β on temperature profile $\theta_2(\eta)$.



Figure 12 Influence of *M* on axial velocity profile $f'(\eta)$.



Figure 13 Influence of *M* on pressure profile $P_1(\eta)$.



Figure 14 Influence of *M* on temperature profile $\theta_1(\eta)$.



Figure 15 Influence of *M* on temperature profile $\theta_2(\eta)$.



Figure 16 Influence of *D* on axial velocity profile $f'(\eta)$.

Figures 16 to 19 portray the effect of various values of curvature parameter on velocity, pressure and temperature distributions, respectively. From Figure 16 it is observed that $f'(\eta)$ increases as curvature is enhanced. This can be explained because when D is increased the radius of cylinder decreases. As a result less resistance is provided on the surface which tumid the fluid velocity in boundary layer region. It discernible from Figures 18 and 19 that temperature profile $\theta_1(\eta)$ is reduced for higher values of curvature parameter but $\theta_2(\eta)$ is enhanced. With increasing values of D we see that pressure profile $P_1(\eta)$ is also increased effectively (Figure 17).

Figures 20 to 23 plotted to observe the impact of magnetic particles volume fraction on velocity, temperature and pressure distributions, respectively. The fluid velocity $f'(\eta)$ decreases with increasing values of volume fraction ϕ . This is due to the fact that magnetic particles spawn friction in fluids that creates a resistance to the flow. Since magnetic particles in large surface area produced high thermal conductivity, as a result thermal boundary layer is increased which is clearly visible in Figure 23 for the temperature profile $\theta_1(\eta)$ whereas the opposite is observed at Figure 22 which pictures the profile





Figure 17 Influence of *D* on pressure profile $P_1(\eta)$.



Figure 18 Influence of *D* on temperature profile $\theta_1(\eta)$.



Figure 19 Influence of *D* on temperature profile $\theta_2(\eta)$.



Figure 20 Influence of ϕ on axial velocity profile $f'(\eta)$.





Figure 21 Influence of ϕ on pressure profile $P_1(\eta)$.



Figure 22 Influence of ϕ on temperature profile $\theta_1(\eta)$.



Figure 23 Influence of ϕ on temperature profile $\theta_2(\eta)$.

of the other temperature component $\theta_2(\eta)$. The pressure profile is gradually decreased with increasing values of volume fraction.

Finally, Figures 24 and 25 represent the effect of the Prandtl number on temperature distributions. From Figures 24 and 25 it's clearly seen that with increasing values of the Prandtl number temperature profiles $\theta_1(\eta)$ and $\theta_2(\eta)$ are reduced. Since Prandtl number is the ratio of momentum to thermal diffusion in boundary layer region.

One other interesting part of the study in engineer view is to graphically represent the skin friction coefficient, rate of heat transfer coefficient and wall pressure gradient. Mathematically, skin friction coefficient and rate of heat transfer coefficient are defined as

$$C_{f} = -\frac{2\tau_{w}}{\rho_{f}U_{w}^{2}}$$

$$Nu_{x} = -\frac{x}{(T_{c} - T_{w})} \left(\frac{\partial T}{\partial r}\right)_{r=a}$$
(31)



Figure 24 Influence of Pr on temperature profile $\theta_1(\eta)$.



Figure 25 Influence of Pr on temperature profile $\theta_2(\eta)$.

Where, $\tau_w = \mu_{mf} (\frac{\partial \mathbf{u}}{\partial r})_{r=a}$ is the wall shear stress, using (16) and (17), Equation (31) reduces into

$$C_f = -\frac{2}{(1-\phi)^{2.5}} \operatorname{Re}^{-\frac{1}{2}} f''(0)$$
(32)

$$Nu_x = -(\theta_1'(0) + \xi^2 \theta_2'(0)) \operatorname{Re}^{\frac{1}{2}}$$
(33)

Here $\text{Re} = \frac{u_0 x^2}{v_f l}$ known as local Reynolds number, f''(0) and $\theta'(0) = (\theta'_1(0) + \xi^2 \theta'_2(0))$ are defined as wall shear and wall heat transfer parameter, respectively.

Figures 26 to 31 demonstrate the skin friction coefficient, rate of heat transfer and wall pressure with M and β in the presence or absence of magnetic particles volume fraction, respectively. Where $P_1(0)$ represent the wall pressure parameter, solid line indicates when $\phi \neq 0$ and dash line signifies when $\phi = 0$. From the Figures 26 to 31 it is apparent that f''(0), $\theta'(0)$ increase when values of M and β are enhanced respectively, whereas $P_1(0)$ is decreased. It also noticed from these figures that f''(0) and $\theta'(0)$ are



Figure 26 Skin friction coefficient -f''(0) with β for various values of M.



Figure 27 Rate of heat transfer $-\theta'(0)$ with β for various values of M.



Figure 28 Wall pressure $P_1(0)$ with β for various values of M.



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Figure 29 Skin friction coefficient -f''(0) with M for various values of β .



Figure 30 Rate of heat transfer $-\theta'(0)$ with M for various values of β .



Figure 31 Wall pressure $P_1(0)$ with M for various values of β .

always seems to be positive and negative, respectively throughout all their variation.

Conclusion

The main objective of the present study is to analyze the magnetic field effect on a base fluid like blood which is electrically conducting, contains magnetic particles and flows above a two-dimensional stretched cylinder in the presence of magnetic dipole. The numerical solution of the given problem carried out with the help of a finite differences method, based on central differencing, tridiagonal matrix manipulation and an iterative procedure. The effects of leading parameters which are involved with this model are studied and represented graphically. Such kind of problems is interesting in biomedicine. From the above analysis the basic conclusions are:

(1) After adding magnetic particles on blood, its flow is reduced, and the temperature is increased significantly using the extended BFD formulation comparatively to that of FHD or MHD.

- (2) The axial velocity is decreased with increasing the values of the ferromagnetic number, magnetic parameter, and volume fraction whereas, is enhanced for large values of the curvature parameter.
- (3) For enlarging values of the ferromagnetic number, magnetic parameter and Prandtl number the temperature profiles are enhanced.
- (4) Opposite influence is observed in temperature profiles for curvature parameter and volume fraction.
- (5) The pressure profile is decreased significantly with enhancing values of the ferromagnetic number, magnetic parameter and volume friction. The reverse behavior is obtained with the variation of the curvature parameter.
- (6) For raising values of ferromagnetic number and magnetic parameter, skin friction coefficient and rate of heat transfer are increased respectively.
- (7) The wall pressure is reduced for higher values of ferromagnetic number and magnetic parameter.

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